

Pioneering Measured Solutions

The LXT 970 & LXT 971 is an easy and affordable entry into torque measurement technology. These are mainly used in testing facilities, automation process, production lines, e.g. end of line tests and research and development. The sensor is provided as a complete unit with integrated electronics, including 5m cable, keystones for round shaft and calibration certificate.



#### **FEATURES**

- Integrated electronic (plug & play)
- Contact-less measurement system
- Including 5m cable and calibration certificate
- Suitable accessories (bracket, readout unit, couplings)

# LXT 970/LXT 971

LXT 970 Square Shaft	Nominal Torque (Nm)	Limiting Torque Unidirectional (Nm)	Limiting Torque Bidirectional (+/-)(Nm)	Rotational Speed (rpm)
	2.5	2.5	2.5	
	5.0	5.0	5.0	
1/4 inch	7.5	7.5	7.5	
	17.5	17	10	1,000'
3/8 inch	75	60	40	]
1/2 inch	175	140	85	
3/4 inch	500	400	270	

Note: Please note that the LXT 970 sensor variants are calibrated to Nominal torque, however, the absolute operational limits for unidirectional and bidirectional loads are as per mentioned in the table above. Do not exceed the mentioned magnitude of limiting torques for unidirectional and bidirectional load. The sensor variants of the LXT 970 will fulfill the CE norms from Q4 2020.

LXT 971 Square Shaft	Nominal Torque (Nm)	Limiting Torque Unidirectional (Nm)	Limiting Torque Bidirectional (+/-)(Nm)	Rotational Speed (rpm)
	2.5	3.25	3.25	
	5	6.5	6.5	
9 mm	7.5	9.75	9.75	
	17.5	19.5	19.5	5.000
14 mm	75	97.5	97.5	
19 mm	175	227.5	227.5	
	250	325	325	
25 mm	500	650	650	

Note: In case of overload, the sensor leads to an offset in measurement. In such case, the sensor needs to be re-calibrated at Group Four. The sensor should be operated only within the specified nominal torque range.

#### **OUPUT RANGE 970**

LXT 970 Measuring Range	Axial Force (N)	Limit Transverse Force (N)	Limit Bending Moment (Nm)	Rotational Speed (RPM)
2.5	1,000	20	2.5	
5	1,000	20	2.5	
7.5	1,000	30	3.7	1.000
15	1,000	100	12.5	1,000
60	2,600	300	41.7	
140	4,000	500	89.5	
400	7,000	800	176	

Outputs Available	0 Torque Output Voltage
A1 Voltage +/- 10V	0 V
A2 Voltage +/- 5V	0 V
A3 Voltage 0-10 V	5 V
A4 Voltage 0-5 V	2.5 V

Order Example: LXT 970-A2 5

LXT 971 Measuring Range	Axial Force (N)	Lateral Limit Force (N)	Bending Limit Moment (Nm)	Rotational Speed (RPM)
2.5	1,000	20	2.5	
5	1,000	20	2.5	
7.5	1,000	30	3.7	
17.5	1,000	100	12.5	5,000
75	2,600	300	41.7	
175	4,000	500	89.5	
500	7,000	800	176	

Outputs Available	0 Torque Output Voltage
A1 Voltage +/- 10V	0 V
A2 Voltage +/- 5V	0 V
A3 Voltage 0-10 V	5 V
A4 Voltage 0-5 V	2.5 V

Order Example: LXT 971-A2 5

Each type of irregular stress can only be permitted with its given limit value (bending moment, lateral force or axial force, exceeding the nominal torque) if none of the others can occur. Otherwise the permitted limits must be reduced. If for instance 30 % of the limited bending moment and also 30 % of the limited lateral force are present, only 40 % of the limited axial force are permitted, provided that the nominal torque is not exceeded.

 $^{2}$  The specified values only apply to direct axial force on the shaft. If the axial force acts on the circlip, only 50% of the force is permitted. <sup>3</sup> The specified values only apply to direct axial force on the shaft. If the axial force acts on the circlip, only 50% of the force is permitted.

## **SPECIFICATIONS**

No.	Model Accuracy Class <sup>4</sup>	Unit	LXT 970/971 1.0 Value							
1	Linearity deviation incl. hysteresis	F				<	<±1.0			
2	Rotational Signal Uniformity (RSU)	%ME <sup>3</sup>	<±1.0							
3	Repeatability					<	±0.05			
	Output Signal in General	Unit				١	/alue			
4	Frequency range, -3dB point, Bessel characteristics	Hz					1,000			
5	Analog signal	V				see ord	lering ta	able		
6	Signal at torque = Zero <sup>6</sup>	V				see ord	lering ta	able		
7	Signal at positive nominal torque <sup>5</sup>	V				see ord	lering ta	able		
8	Signal at negative nominal torque <sup>5</sup>	V				see ord	lering ta	able		
9	Calibration parameter (normed) <sup>5</sup>	mV/N m			Refer	to Calil	oration (	Certific	ate	
10	Output resistance						50			
	Effect of Temperature	Unit	Value							
11	Zero point drift over temperature	%/10K	<0.5							
12	Signal drift over temperature within nominal temperature range	%/10K	<0.5							
	Power Supply	Unit	Value							
13	Supply voltage	VDC	615							
14	Current consumption (max.)	mA					10			
15	Start-up peak	mA					<40			
16	Absolute max. supply voltage	VDC					18			
	General Information	Unit				١	<i>l</i> alue			
17	Protection class according to EN 60529 <sup>7</sup>	IP					50			
18	Reference temperature	°C				+15	5 +35	i		
19	Operational temperature range	°C				-40	+85			
20	Storage temperature range	°C				-40	+85			
	Nominal Torque (bi-directional square shaft)	Nm	2.5	5	7.5	15	60	14	40	400
21	Weight	g	395		401	414	652	7!	54	878
22	Moment of inertia	g mm²	58	582 648 904 3.339 13.294 57.		57.770				
	Nominal Torque (bi-directional round shaft)	Nm	2.5	5	7.5	15	75	175	250	500
23	Weight	g	38	6	392	400	685	8	56	1.230
24	Moment of inertia	g mm <sup>2</sup>	662		662	1.073	4.922	19.	126	79.754

<sup>4</sup>The accuracy class implies that taken separately both the linearity deviation as well as the rotational signal uniformity are either lower than or equal to the value of the accuracy class. <sup>5</sup> %ME: related to a full scale measurement range. <sup>6</sup> Please check the exact data at the sensors calibration certificate.

7 Wiring connected.



Do not loosen or tighten the mounting nuts of the socket and the lock screws.

Dimensions	LXT 970 square shaft normal torque (Nm)				LXT 971	round sh (N	aft norma m)	torque
Shaft size	1/4 IN	3/8 IN	1/2 IN	3/4 IN	Ø 9mm	Ø 14mm	Ø 19mm	Ø 25mm
Nominal torque (Nm)	2.5 - 5 - 7.5 - 17.5	60	140	400	2.5 - 5 - 7.5 -17.5	75	175-250	500
A	95.5	107	123.5	146	125	139	179	220
В	70	70	70	87	70	70	70	87
С	9.5	13	18.5	29.6	27.5	34.5	54.5	66.6
D	-	-	-	-	9k6	14k6	19k6	25k6
E	40	50	50	60	40	50	50	60
F	16	24	35	29.6	-	-	-	-
G	8	8	8	10.5	8	8	8	10.5
Н	5	5	5	2	5	5	5	2
K	12	18	24	33.5	-	-	-	-
L	-	-	-	-	23	30	50	= C
М	43.9	43.9	43.9	61.4	43.9	43.9	43.9	61.4
N	15	18	18	19	15	18	18	19
Р	37	47	47	57	37	47	47	57
S	1.5	1.5	1.5	1.5	1.5	1.5	1.5	1.5

Dimer		Keystones	;			
Round Shaft	Width	Depth	Length	Height	Length	Amount
Ø 9mm	3	1.8	18.5	3	18	1
Ø 14 mm	5	3	25.5	5	25	1
Ø 19 mm	6	3.5	45.5	6	45	1
Ø 25 mm	8	4	50.5	7	50	2



In the case of high alternating loads, torque transmission through a positive and frictional connection with the shaft via a suitable fit or a coupling is recommended.

# **CONNECTION PLAN**



Connector Power supply and outputs

Туре	Binder series s712-M9 connector IP67 color coding according to DIN 47100					
Pin	Code	Code Pin				
1	White	Supply Voltage Vcc	6V - 15V			
2	Brown	Signal Output Analogue	-			
3	Black	Ground GND	-			
4	Blue	Not Used	-			
5	Grey	Reference Voltage Vref	2,5 V			

The output Vref is a constant 2.5 V and represents the virtual zero point for direct +/- torque measurement.

Connection example:

Connection for measurement between 0.5 .... 4.5 V e.g. 2.5V equals to approx. 0 Nm.

Grey and blue wires are not in use.

Connection for measurement between - 2.0 ... +2.0 V e.g. 0 V equals to approx. 0 Nm.

Blue wire is not in use.



LXT 970/971 accessories					
Sensor Bracket					
1	2.5 - 17.5 Nm LXT-SB-17				
2	75 - 250 Nm LXT-SB-250				
Readout Unit	• •				
1	DFI 3000-A	The readout unit is a multi-functional readout unit dedicated for the Group Four LXT series. Torque, angle or speed can be displayed. The measurement data can be stored on an inserted SD flash memory card or sent directly to a PC computer via USB interface in real time.			
Couplings	•				
Coupling Types	Used for	D2 max			
LXT-45	2000-D9	15			
LXT-100	2000-D9	25			
LXT-18	2000-D9	25.4			
LXT-80	2000-D14	42			
LXT-200	2000-D19	45			
LXT-300	2000-D19	60			
LXT-500	2000-D25	70			

### **INSTRUCTION MANUAL**

## **Scope of delivery**

The torque sensor set consists of the sensor itself (signal pick-up and signal processing integrated into sensor housing), one connecting cable 5 m with a soldered plug (binder plug no. 99-0426-10-08), key stones (round shaft) or square sleeve (Square shaft) and the calibration certificate.

### Installation and removal

It must be ensured that when mounting the sensor, the measuring shaft is exactly aligned with the connecting shafts (corresponding couplings can be found in the accessories). The key adapters / square ends of the connecting shafts must then be able to be pushed onto the key adapter connections / square connections of the sensor without any effort. When fastening, no force may be exerted on the housing in the axial direction. The key surfaces are to be used to secure the sensor against twisting (optional sensor holder). The cable length may be max. 5 m. If a cable other than the one supplied by Group Four or the same cable with a different cable length is used, the function of the sensor system may be impaired.

Do not remove the shaft with torque applied to the sensor.

# **Interface description**

#### Mechanical connection:

The key stone adapters on both ends of the measurement shaft are intended for torque transmission.

#### Electrical connector:

On the sensor housing there is a socket for the power supply and the signal output (see chapter connection plan).

#### Operation (in regular case or in optimal case)

Optimal measurement parameters can be achieved if the sensor is applied in accordance to the specification. By compliance with the specification the sensor works generally trouble-free and maintenance-free.

#### Irregular operation, measures against disturbance

The mechanical overload on the sensor (e.g. exceeding of maximum allowed torque or severe vibrations) may cause damage to the sensor and in consequence the incorrect signal output. In such cases please do not open the sensor. Contact Group Four directly for assistance.

#### Commissioning

After sensor installation pay attention to the following:

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- Switch on the power supply and check the voltage value (voltage peaks on the sensor must be avoided, devices must be checked accordingly before connection to the sensor).
- Connect the sensor to the power supply unit by using the delivered cable.
- Connect the sensor output to a high-resistance device such as an A/D converter, oscilloscope, pc measurement board.
- The sensor should be in mechanical unloaded state while connecting it.

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# Shaft coating

The shafts are protected on both sides with a film of anti corrosion wax. We recommend to leave the protection permanent. As far as technologically needed, the coating can be removed with spirit / ethanol.

## Handling and transportation

During handling, storage and transportation, make sure that the sensor is not exposed to strong magnetic or electromagnetic fields (e.g. demagnetizing coils).

#### **Precautions**

- Do not open the sensor housing under any circumstances.
- The shaft locking rings on the shaft ends must not be loosened.
- The fastening nut of the plug (see chapter Dimensions) must not be loosened or tightened.
- Only use voltage supplies that are separate from the mains voltage.
- With regard to the electrical and mechanical load on the sensor, the specifications in accordance with the sensor-specific rating plate and the table in (Chapter: Technical characteristics) must be observed.
- The sensor is not to be used as a support bearing. The existing mounting options are only used to secure the housing against turning.
- To protect your system, we recommend increasing the torque over several stages.

#### Service and maintenance

As part of your test and measurement equipment management, we recommend regular inspection of your test and measurement equipment. Please also note the relevant standards and guidelines.

#### **Recommended maintenance**

Recalibration - 12 month Inspection of wiring, plug and shaft - 12 month Email: sales@group-4.com

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